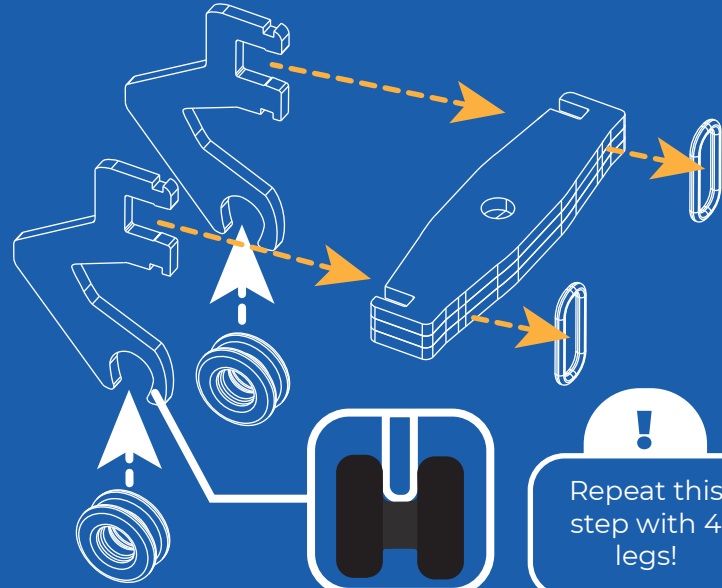


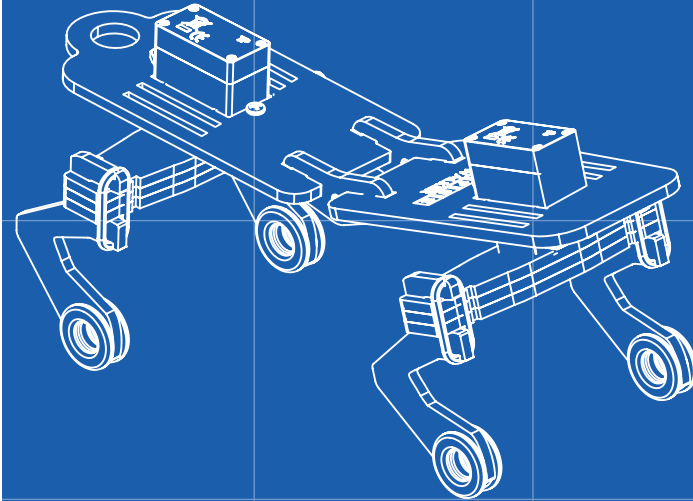
Mission: Robotics Expedition Kit

WALKER

1 ● ○ ○ ○

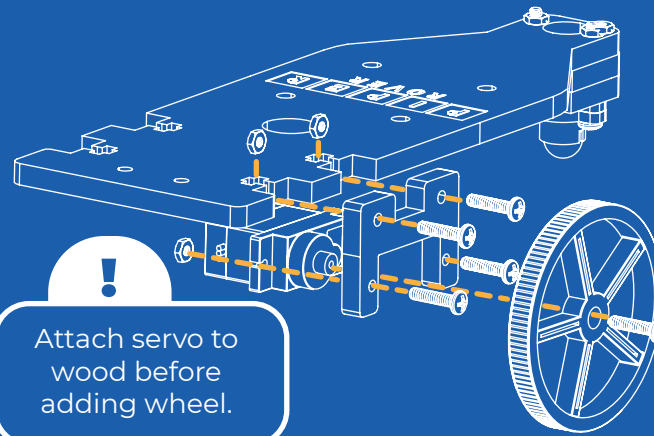


Repeat this step with 4 legs!

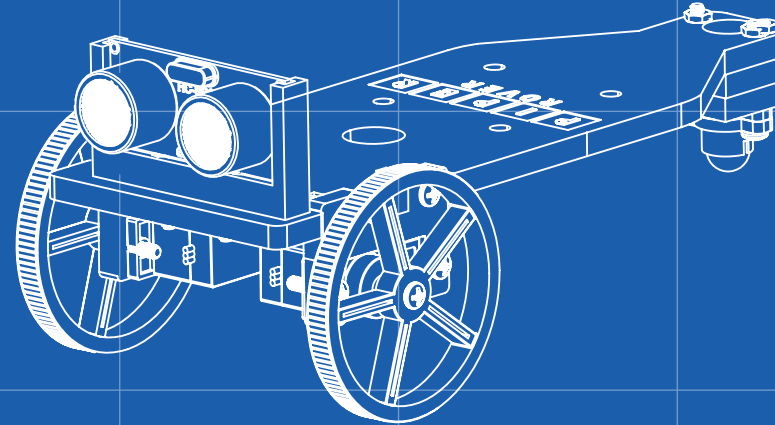


After assembly, head to MAKE.PLAYPIPER.COM to get started with your Walker and Rover!

1 ● ○



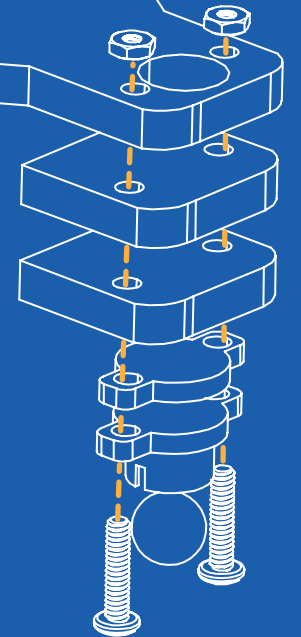
ROVER



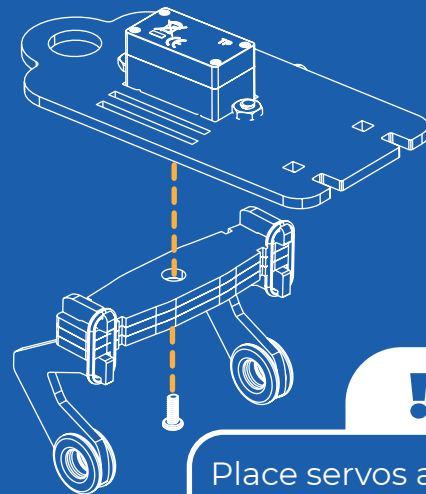
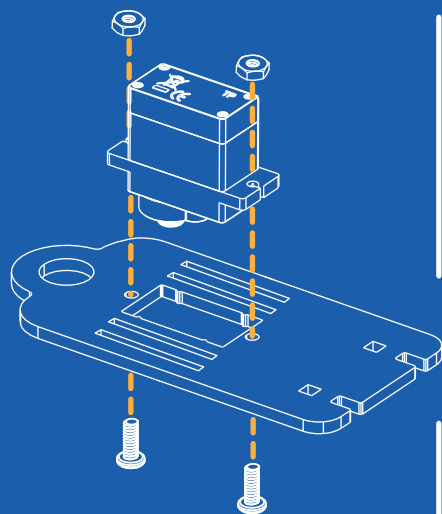
2 ● ●

NOTE

Make sure the ball fits into the holder before screwing in.

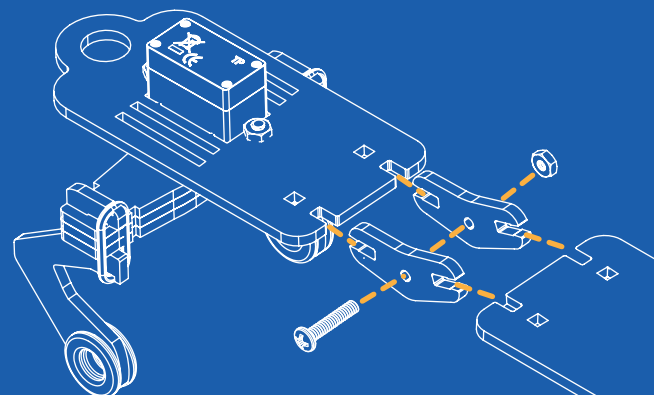


2 ● ● ○



Place servos away from center.

3 ● ● ●



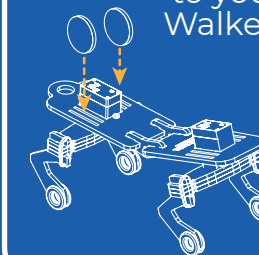
Do not overtighten the screw!

CUSTOMIZATIONS

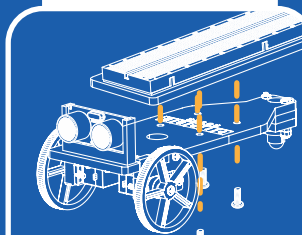
The **Ultrasonic Range Finder** and **3D printed holder** can be attached to either your Walker or Rover!

WALKER

Add coins to your Walker!



ROVER



Attach your Starter Base to your Rover

