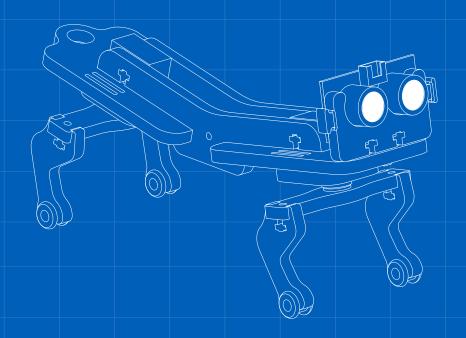


Mission:

Piper Make Robotic Walker

SIDE A

Assembly





1 Torso 1 O-Ring

1 Trunk 2 FS90 Servo Motor

4 Legs **6** #4-40 Screws (A)

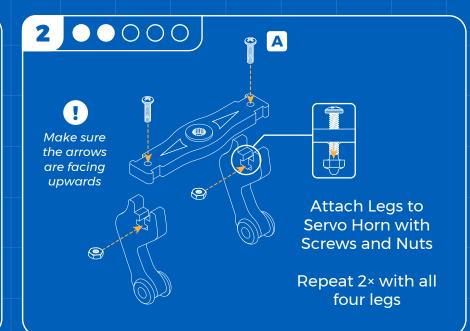
4 Grommet 2 Small Screws (B)

2 Servo Horn 4 #4-40 Screws (C)

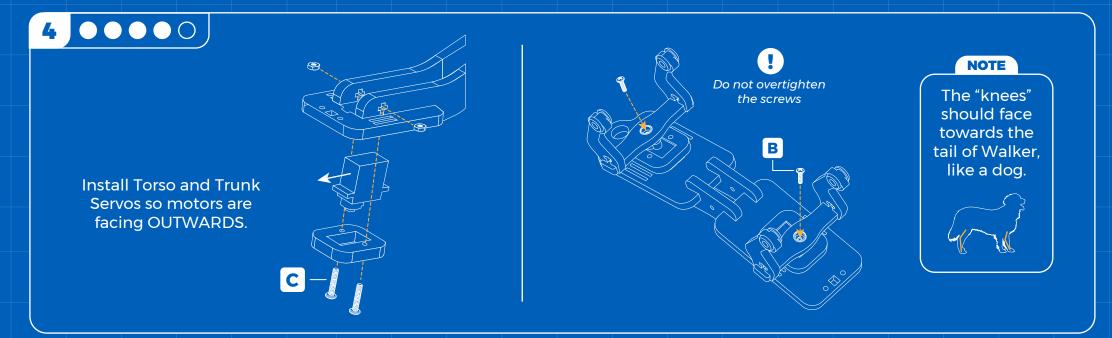
2 Servo Holder 10 Hex Nuts

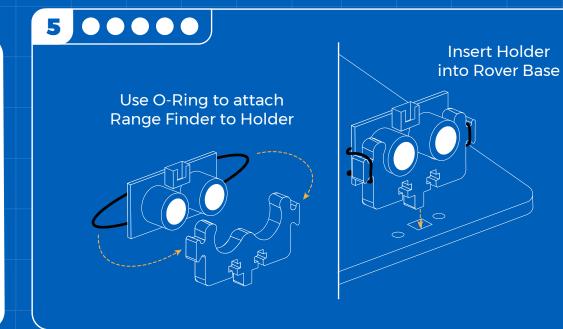
2 Spine 1 Ultrasonic Range Finder

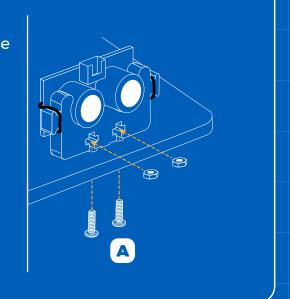












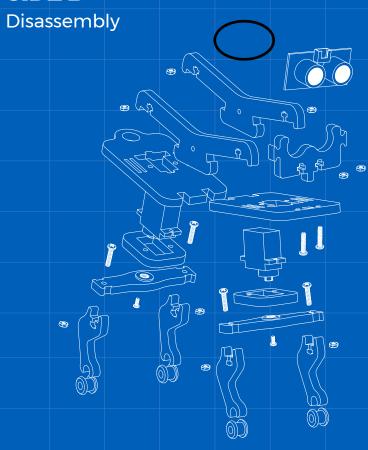


P I P E R

Mission:

Piper Make Robotic Walker

SIDE B



INVENTORY

1 Torso 1 O-Ring

1 Trunk 2 FS90 Servo Motor

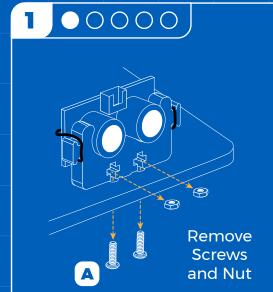
4 Legs **6** #4-40 Screws (A)

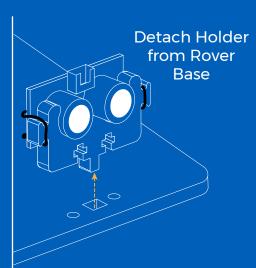
4 Grommet 2 Small Screws (B)

2 Servo Horn 4 #4-40 Screws (C)

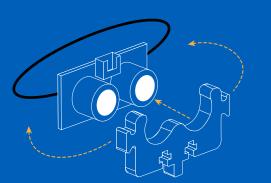
2 Servo Holder 10 Hex Nuts

2 Spine 1 Ultrasonic Range Finder

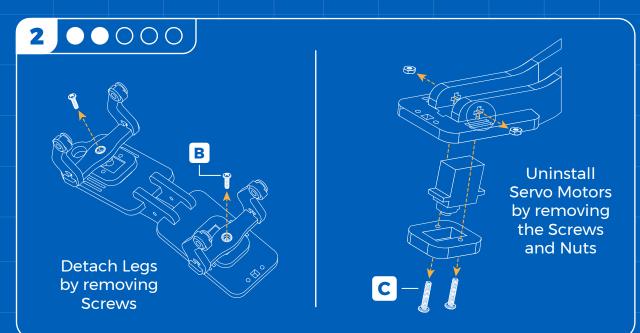


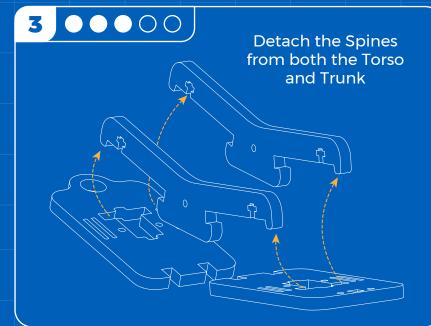


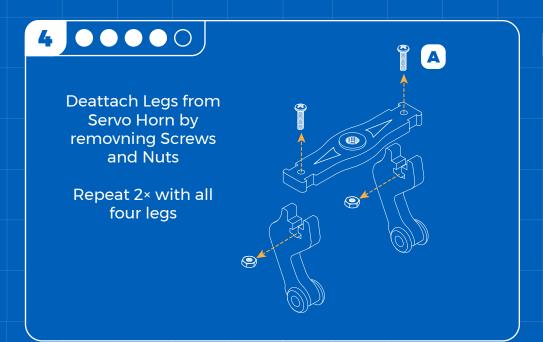
Remove O-Ring to detach Range Finder from Holder



Place each item on its spot on the Components sheet









DISASSEMBLY COMPLETE!

If not already done, place each piece on its spot on the Components sheet

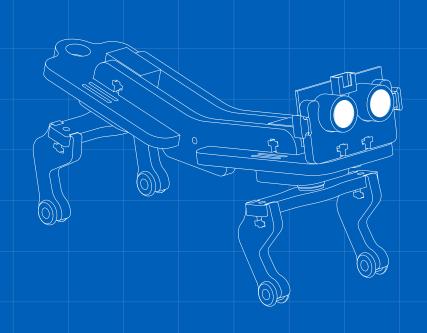


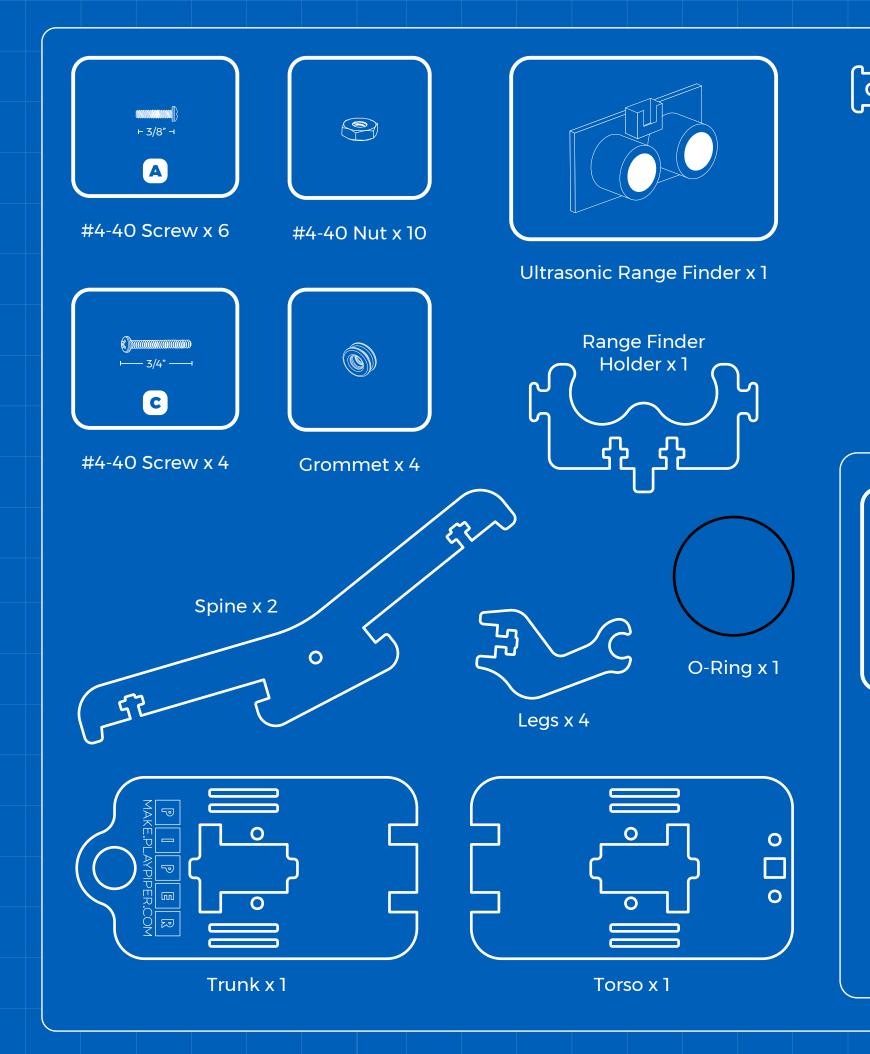
Mission:

Piper Make Robotic Walker

Components Sheet

Gather and organize your supplies





Servo Horn x 2

Servo Holder x 2

Servo Motors

FS90R Servo Motor x 2

В

Small Screws x 2

Piper Make Robotic Walker Version 1.0.1